

Neural network prediction of relativistic electrons at geosynchronous orbit during the storm recovery phase: effects of recurring substorms

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Abstract. During the recovery phase of geomagnetic storms, the flux of relativistic (>2 MeV) electrons at geosynchronous orbits is enhanced. This enhancement reaches a level that can cause devastating damage to instruments on satellites. To predict these temporal variations, we have developed neural network models that predict the flux for the period 1–12 h ahead. The electron-flux data obtained during storms, from the Space Environment Monitor on board a Geostationary Meteorological Satellite, were used to construct the model. Various combinations of the input parameters AL , ΣAL , D_{st} and ΣD_{st} were tested (where Σ denotes the summation from the time of the minimum D_{st}). It was found that the model, including ΣAL as one of the input parameters, can provide some measure of relativistic electron-flux prediction at geosynchronous orbit during the recovery phase. We suggest from this result that the relativistic electron-flux enhancement during the recovery phase is associated with recurring substorms after D_{st} minimum and their accumulation effect.

Key words. Magnetospheric physics (energetic particles, trapped; magnetospheric configuration and dynamics; storms and substorms)

1 Introduction

During the recovery phase of geomagnetic storms, the flux of relativistic (>2 MeV) electrons at geostationary orbits (GEO) is enhanced. This enhancement often reaches a level that is higher than the prestorm value (e.g. Nagai, 1988; Baker et al., 1997; Obara et al., 2000a). This enhancement is not accounted for by the flux of energetic electrons in the interplanetary medium alone (Li et al., 1997). This implies that some energization or transportation process operates on the energetic electrons in the magnetosphere. Although the

mechanism for this process has been suggested by several researchers (e.g. Freeman et al., 1998; Nakamura et al., 1998; Obara et al., 2000b), there is still considerable uncertainty about the details.

High flux levels of relativistic electrons can cause irreparable damage to the instruments on satellites (Gussenhoven et al., 1991; Baker et al., 1997), and this practical consequence of the flux enhancement has promoted the development of empirical models. Nagai (1988) designed a linear prediction filter for the prediction of daily averages of electron flux at GEO, using the K_p index as an input. This model predicted successfully the electron flux on a daily scale. Koons and Gorney (1991) also made predictions of the daily average flux at GEO using artificial neural networks (ANN).

Modeling using ANN has predicted successfully the energetic-electron flux with a time resolution of 1 h (Stringer et al., 1996; Freeman et al., 1998). Although the energy range of the electrons for these two models is different (3–5 MeV for Stringer et al., 1996 and 100 keV to 1.5 MeV for Freeman et al., 1998), both models used the D_{st} index, and the electron flux as input data. Stringer et al. (1996) used the current flux of energetic electrons (3–5 MeV), and those which existed 1 to 3 h earlier. Freeman et al. (1998) used the current low-energy (35 keV) electron flux, plus those existing 15 min and 75 min earlier, to predict the energetic (100 keV to 1.5 MeV) electron flux for the storm of 3–4 November 1993. It would appear that the high performance of these models is due to the inclusion of the variation of electrons existing earlier as data. Since the use of the model has important practical applications, it not only needs to help us understand the physical mechanism, but also must use widely available input parameters. In this paper, we show ANN modelling of the relativistic-electron flux for the recovery phase is possible using ΣAL (the summation of AL from the time of D_{st} minimum in the main phase), and we suggest the significance of recurring substorms in the flux enhancement.

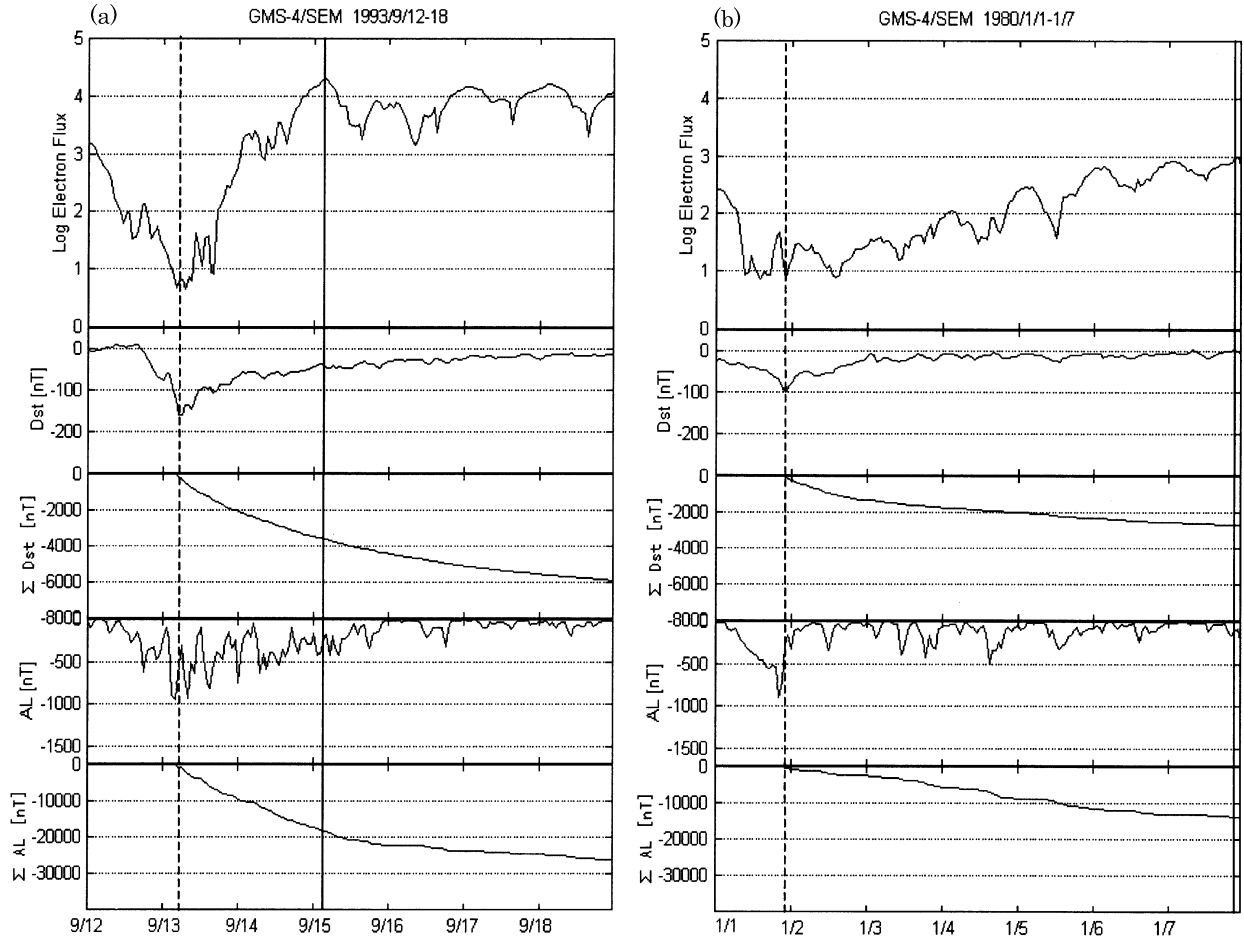


Fig. 1. Examples of enhancements of relativistic (>2 MeV) electron flux observed by Geostationary Meteorological Satellite and D_{st}/AL indices **(a)** for the the storm of 12–18 September 1993, and **(b)** for the storm of 1–7 January 1980. ΣD_{st} and ΣAL are also plotted, where Σ denotes the summation from the time of the minimum D_{st} . The minimum D_{st} is represented with a dashed vertical line, and a solid line represents the time for the peak electron flux for the six-day period after the D_{st} minimum.

2 AL index as model input

We used data for relativistic (>2 MeV) electrons that were obtained from the Space Environment Monitor of Geostationary Meteorological Satellite (GMS), located at about 140° E. From the GSM data between August 1978 and August 1998, we selected 29 storm events, by examining the D_{st} index variations. Figure 1 shows two examples from the 29 storms, where the logarithms of electron flux, D_{st} , ΣD_{st} , AL , and ΣAL are plotted from top to bottom, respectively. For the AL and ΣAL , we used the hourly average AL index.

Figure 1a shows that the electron flux reaches a maximum of more than 10^4 count $\text{cm}^{-2}\text{sec}^{-1}\text{sr}^{-1}\text{MeV}^{-1}$ about 2 days after the D_{st} minimum. In Fig. 1b, the electron flux about 2 days after the D_{st} minimum is still low. When we compare D_{st} , ΣD_{st} , AL , and ΣAL in the region of the flux maximum for Fig. 1a with those for Fig. 1b, it is evident that there is a significant difference. In Fig. 1b, AL does not exceed 500 nT after the D_{st} minimum, whereas for Fig. 1a, such large values of AL occur several times. Consequently, the magnitude of

ΣAL between the two sets of conditions is rather different: in Fig. 1a, the magnitude of ΣAL about 2 days after the D_{st} minimum (at the solid vertical line) is more than three times as large as its magnitude at the same time in Fig. 1b. These facts suggest that AL and ΣAL serve as proxies for factors that influence the peak electron flux.

For each storm event, we examined the peak electron flux for the six-day period after the D_{st} minimum, and the corresponding magnitude of ΣAL . Figure 2 shows scatter plots of the electron flux (logarithmic scale) against the magnitude of ΣAL , for all 29 storm cases. Although log flux values greater than 4 occur for a wide range of $|\Sigma AL|$ (from 18 000 to 43 000), the electron flux tends to be large with increasing $|\Sigma AL|$. The correlation coefficient (CC) is calculated to be 0.64. This rough correlation supports the proposition that ΣAL may be a measure of the control factors in determining the peak electron flux. We also checked if ΣD_{st} shows a similar correlation, but a clear relation was not identified (CC = 0.11).

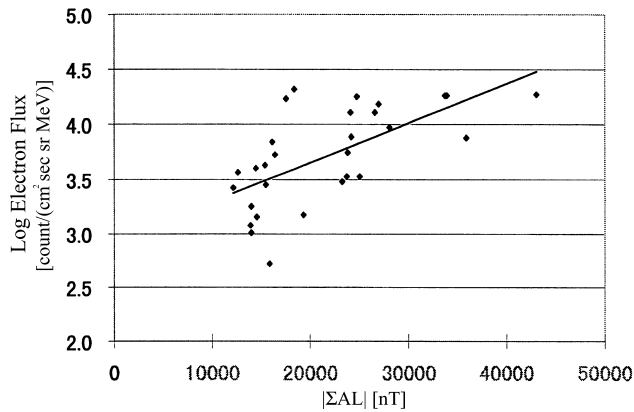


Fig. 2. Scatter plots of the peak electron flux versus the absolute value of ΣAL for all 29 events. The solid line indicates the least-squares fit.

3 ANN model construction and performance

In order to construct an ANN model for the relativistic electron flux, we adopted AL , ΣAL , D_{st} , ΣD_{st} , and UT ($= LT - 9\text{h}$ for GMS) as input parameters. The D_{st} index is known to be one of the important parameters that determines the maximum electron flux (e.g. Reeves, 1998). The importance of the history of D_{st} has been suggested by Stringer et al. (1996), and Freeman et al. (1998), although simple comparison between ΣD_{st} and the peak electron flux does not necessarily identify a clear relation between them. UT is used in the form of $\sin(UT/24)$, in order to reproduce a daily variation (or LT dependent structure) of the flux. The recent history of the five parameters was fed to the model. We used an Elman ANN, which is known as a two-layer back-propagation network with feedback connections from the hidden layer to the input layer (Elman, 1990; Wu and Lundstedt, 1997; Kugblenu et al., 2001). The hidden layer has the context neurons, as well as the true input neurons, and the context neurons act as an integrator of temporal information dating back to its initial state; i.e. this gives the network a nonlinear memory capacity.

For the data set for the network training, we selected nine of the 29 storm events in such a manner that the training data set could have various types of flux variations. The nine events consisted of storms on 28 August 1978, 1 January 1980, 6 February 1980, 3 November 1985, 29 November 1985, 4 June 1993, 4 November 1993, 4 April 1994, and 17 April 1994. A total of 1043 h from these nine events was used for the training. As the learning parameters for training, we chose an RMS error goal of 0.01, an initial adaptive learning ratio of 0.001, an increasing rate-of-learning ratio of 1.05, a decreasing rate-of-learning ratio of 0.7, a momentum constant of 0.95, an error ratio of 1.04, and used 5000 learning cycles.

First, we constructed the model for one-hour forward prediction. The performance of the model was then evaluated by comparing the predictions with the observations for the

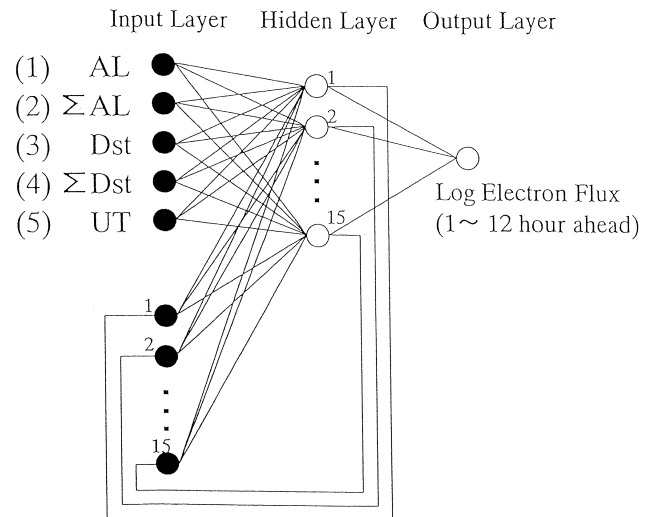


Fig. 3. Architecture of the optimized Elman neural network.

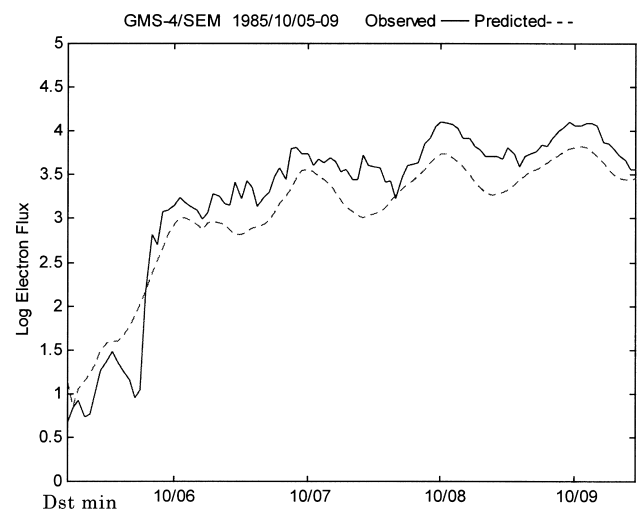


Fig. 4. The storm of 5–9 Oct 1985 for which the best predictability was obtained. The solid and dashed curves represent the observation and one-hour forward prediction, respectively.

remaining 20 storm events (2146 h). It was found that the optimized ANN had the design shown in Fig. 3, i.e. the number of hidden neurons was 15. This ANN model produced both the highest average value of CC (between the predicted and observed variations), and the highest prediction efficiency (PE) for the 20 test cases. The average values for CC and PE were 0.84 and 0.71, respectively. The average of the RMS error was 0.47. Figure 4 shows a storm for which this ANN model produced the highest CC (0.97) and PE (0.86) of all the 20 cases. The prediction (dashed curve) follows the observation (solid curve) reasonably well, although the model does not capture the steepness of the rise in flux on 5 October.

We also made some other training data sets by adding several storms to the nine events, and checked the ANN model's performance. The increase in the number of the training data sets did not necessarily improve the prediction performance

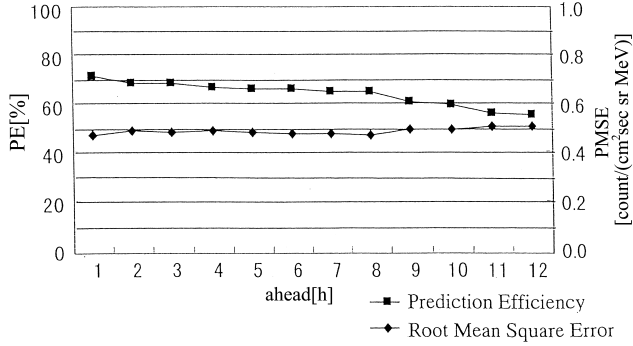


Fig. 5. Change of prediction efficiency (PE) and root-mean-square error (RMSE) for the period 1 to 12 h ahead.

of the model. However, when we reduced the number of the training data sets, the performance became worse. Although this may be dependent on which storms are included in the training data sets, it is likely that the selected nine events for the training cover various types of flux enhancements.

To identify which input parameters were the most crucial, we dropped D_{st} and AL from the input parameters, and designed a new ANN. In this model, PE was approximately 0.71, the same as for the original model. Then, we also dropped ΣD_{st} from the inputs, i.e. the model had only two inputs, ΣAL and UT. For this model, PE was about 0.68, and still close to the original value, indicating that the effect of ΣD_{st} is not very strong. Next, we dropped ΣAL instead of D_{st} , i.e. two input parameters, ΣD_{st} , and UT, were used. For this model, the prediction efficiency became 0.47, which is much lower than the original efficiency of 0.71. We also designed a model with only the ΣAL index as the input parameter, i.e. no UT input. The prediction efficiency was 0.64, which is just below the value of 0.68 that was obtained using the model with ΣAL and UT as inputs. From these results, ΣAL proved to be the most crucial factor for the flux-enhancement. It should be noted, however, that this ΣAL is the quantity after D_{st} minimum, by which storm times were identified in the first place.

Using the ANN model with inputs of ΣAL , ΣD_{st} , and UT, we attempted to predict the electron fluxes for the period 2 to 12 h ahead. The results are summarized in Fig. 5. Although PE gradually decreased from 0.71 as the prediction time increased, it was 0.60 or more for the predictions up to 9 h. Similar ratios and trends were obtained with the five-input model.

If real-time D_{st} and AL are available, our model can be used for real-time operation. For this, it should be noted that the model starts to produce outputs several hours after the time of D_{st} minimum, since it is not until D_{st} recovers to a certain degree that we can determine the time of D_{st} minimum. However, this delay does not cause a significant problem for the flux prediction, since the flux usually reaches a maximum much later than such a short period of time.

Using a neural network, Koons and Gorney (1991) have shown that up to 10 days of inputs are required to model

accurately the electron flux. Our model is not inconsistent with their result. Our model includes ΣD_{st} and ΣAL as inputs. Although neural network feedback of our model is a one-hour step (Fig. 3), these two parameters can have the history of D_{st} and AL from the time of D_{st} minimum. The maximum of the electron flux usually occurs a few days or more after D_{st} minimum, and this means that D_{st} and AL for several days of inputs are used to model.

4 Concluding remarks

We have predicted successfully the electron flux using an Elman recurrent-ANN with inputs of AL , ΣAL , ΣD_{st} , D_{st} and UT, or with inputs of ΣAL , ΣD_{st} , and UT. The feedback connections of the ANN can model effectively the enhancement of the electron flux as a function of the above input parameters, in particular, ΣAL . The substorm effect represented by ΣAL (i.e. the accumulation effect of AL history after D_{st} minimum) has a significance influence on the flux enhancement in the recovery phase.

It has been accepted that substorms occur more often during southward IMF than northward IMF (e.g. Kamide et al., 1977), although all substorms are not triggered by southward turnings of IMF (e.g. Rostoker, 1983; Lyons et al., 1997). This may appear to indicate that ΣAL effects simply reflect the accumulation effect of southward IMF. It should be noted, however, that $|AL|$ tends to be large with the increase in solar wind speed, as well as with the increase in the southward IMF component (e.g. Maezawa and Murayama, 1986). They showed that velocity dependence of the AL index is steeper than linear, approximately proportional to V^2 . Hence, our result that the substorm effect represented by ΣAL has a significance influence on the flux enhancement is not inconsistent with the result obtained by Paulikas and Blake (1979), who showed that there is a good correlation between the solar wind velocity and the MeV electron flux. Some recent papers (e.g. Li et al., 2001) also have indicated the significance of the solar wind speed for the electron flux.

Several researchers (e.g. Baker et al., 1997; Nakamura et al., 1998; Obara et al., 2000b) have suggested that during the main phase, the inward transport of intermediate-energy electrons occurs, and that seed electrons form. This main-phase transport process may be related to substorm activity, such as substorm injections. Our results suggest that as far as the flux level in the recovery phase is concerned, such a substorm process in the main phase of the storm is not important. Rather, recurring substorms after the storm maximum, or the related magnetospheric state, determine to what extent the electrons, which presumably formed in the main phase, are energized.

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